

15.9: Problems

? Problem 15.9.1

Given

$$\mathbf{A} = \begin{pmatrix} 2 & 3 & -1 \\ -5 & 0 & 6 \\ 0 & 2 & 3 \end{pmatrix}; \mathbf{B} = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}; \mathbf{C} = \begin{pmatrix} 0 & 1 \\ 2 & 0 \\ -1 & 3 \end{pmatrix}$$

Multiply all possible pairs of matrices.

? Problem 15.9.2

The matrix representation of a spin 1/2 system was introduced by Pauli in 1926. The Pauli spin matrices are the matrix representation of the angular momentum operator for a single spin 1/2 system and are defined as:

$$\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}; \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}; \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

1. Show that $\sigma_x \sigma_y = i \sigma_z$, $\sigma_y \sigma_z = i \sigma_x$ and $\sigma_z \sigma_x = i \sigma_y$
2. Calculate the commutator $[\sigma_x, \sigma_y]$.
3. Show that $\sigma_x^2 = \sigma_y^2 = \sigma_z^2 = \mathbf{I}$, where \mathbf{I} is the identity matrix. Hint: as with numbers, the square of a matrix is the matrix multiplied by itself.

? Problem 15.9.3

The inversion operator, \hat{i} transforms the point (x, y, z) into $(-x, -y, -z)$. Write down the matrix that corresponds to this operator.

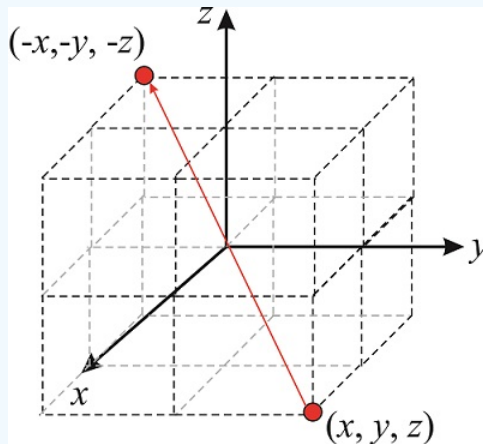


Figure 15.9.1: The inversion operator (CC BY-NC-SA; Marcia Levitus)

? Problem 15.9.4

Calculate the inverse of \mathbf{A} by definition.

$$\mathbf{A} = \begin{pmatrix} 1 & -2 \\ 0 & 1 \end{pmatrix}$$

? Problem 15.9.5

Calculate the inverse of \mathbf{A} by definition.

$$\mathbf{A} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

? Problem 15.9.6

Find the eigenvalues and normalized eigenvectors of

$$\mathbf{M}_1 = \begin{pmatrix} 2 & 0 \\ 0 & -3 \end{pmatrix}$$

$$\mathbf{M}_2 = \begin{pmatrix} 1 & 1+i \\ 1-i & 1 \end{pmatrix}$$

? Problem 15.9.7

Given,

$$\mathbf{M}_3 = \begin{pmatrix} 1 & 1-i \\ 1+i & 1 \end{pmatrix}$$

1. Show that the matrix is Hermitian.
2. Calculate the eigenvectors and prove they are orthogonal.

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