

7.6: Appendix - Review of Free Electromagnetic Field

Here we review the derivation of the vector potential for the plane wave in free space. We begin with [Maxwell's equations](#) (SI):

$$\nabla \cdot \vec{B} = 0 \quad (7.6.1)$$

$$\nabla \cdot \vec{E} = \rho / \epsilon_0 \quad (7.6.2)$$

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \quad (7.6.3)$$

$$\nabla \times \vec{B} = \mu_0 \vec{J} + \epsilon_0 \mu_0 \frac{\partial \vec{E}}{\partial t} \quad (7.6.4)$$

Here the variables are: \vec{E} , electric field; \vec{B} , magnetic field; \vec{J} , current density; ρ , charge density; ϵ_0 , electrical permittivity; μ_0 , magnetic permittivity. We are interested in describing \vec{E} and \vec{B} in terms of a vector and scalar potential, \vec{A} and ϕ .

Next, let's review some basic properties of vectors and scalars. Generally, vector field \vec{F} assigns a vector to each point in space. The [divergence](#) of the field

$$\nabla \cdot \vec{F} = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z} \quad (7.6.5)$$

is a scalar. For a scalar field ϕ , the gradient

$$\nabla \phi = \frac{\partial \phi}{\partial x} \hat{x} + \frac{\partial \phi}{\partial y} \hat{y} + \frac{\partial \phi}{\partial z} \hat{z} \quad (7.6.6)$$

is a vector for the rate of change at one point in space. Here

$$\hat{x}^2 + \hat{y}^2 + \hat{z}^2 = \hat{r}^2 \quad (7.6.7)$$

are unit vectors. Also, the curl

$$\nabla \times \vec{F} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_x & F_y & F_z \end{vmatrix} \quad (7.6.8)$$

is a vector whose x , y , and z components are the circulation of the field about that component. Some useful identities from vector calculus that we will use are

$$\nabla \cdot (\nabla \times \vec{F}) = 0 \quad (7.6.9)$$

$$\nabla \times (\nabla \phi) = 0 \quad (7.6.10)$$

$$\nabla \times (\nabla \times \vec{F}) = \nabla(\nabla \cdot \vec{F}) - \nabla^2 \vec{F} \quad (7.6.11)$$

Gauge Transforms

We now introduce a vector potential $\vec{A}(\vec{r}, t)$ and a scalar potential $\phi(\vec{r}, t)$, which we will relate to \vec{E} and \vec{B} . Since

$$\nabla \cdot \vec{B} = 0 \quad (7.6.12)$$

and

$$\nabla(\nabla \times \vec{A}) = 0, \quad (7.6.13)$$

we can immediately relate the vector potential and magnetic field

$$\vec{B} = \nabla \times \vec{A} \quad (7.6.14)$$

Inserting this into Equation [7.6.3](#) and rewriting, we can relate the electric field and vector potential:

$$\vec{\nabla} \times \left[\vec{E} + \frac{\partial \vec{A}}{\partial t} \right] = 0 \quad (7.6.15)$$

Comparing Equations 7.6.15 and 7.6.10 allows us to state that a scalar product exists with

$$\vec{E} = -\frac{\partial \vec{A}}{\partial t} - \nabla \varphi \quad (7.6.16)$$

So summarizing our results, we see that the potentials \vec{A} and φ determine the fields \vec{B} and \vec{E} :

$$\vec{B}(\vec{r}, t) = \vec{\nabla} \times \vec{A}(\vec{r}, t) \quad (7.6.17)$$

$$\vec{E}(\vec{r}, t) = -\vec{\nabla} \varphi(\vec{r}, t) - \frac{\partial}{\partial t} \vec{A}(\vec{r}, t) \quad (7.6.18)$$

We are interested in determining the classical wave equation for \vec{A} and φ . Using Equation 7.6.17, differentiating Equation 7.6.18 and substituting into Equation 7.6.4, we obtain

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{A}) + \epsilon_0 \mu_0 \left(\frac{\partial^2 \vec{A}}{\partial t^2} + \vec{\nabla} \frac{\partial \varphi}{\partial t} \right) = \mu_0 \vec{J} \quad (7.6.19)$$

Using Equation 7.6.11,

$$\left[-\vec{\nabla}^2 \vec{A} + \epsilon_0 \mu_0 \frac{\partial^2 \vec{A}}{\partial t^2} \right] + \vec{\nabla} \left(\vec{\nabla} \cdot \vec{A} + \epsilon_0 \mu_0 \frac{\partial \varphi}{\partial t} \right) = \mu_0 \vec{J} \quad (7.6.20)$$

From Equation 7.6.16 we have

$$\vec{\nabla} \cdot \vec{E} = -\frac{\partial \vec{\nabla} \cdot \vec{A}}{\partial t} - \vec{\nabla}^2 \varphi \quad (7.6.21)$$

and using Equation 7.6.2,

$$\frac{-\partial \vec{\nabla} \cdot \vec{A}}{\partial t} - \vec{\nabla}^2 \varphi = \rho / \epsilon_0 \quad (7.6.22)$$

Notice from Equations 7.6.17 and 7.6.18 that we only need to specify four field components (A_x, A_y, A_z, φ) to determine all six \vec{E} and \vec{B} components. But \vec{E} and \vec{B} do not uniquely determine \vec{A} and φ . So we can construct \vec{A} and φ in any number of ways without changing \vec{E} and \vec{B} . Notice that if we change \vec{A} by adding $\vec{\nabla} \chi$ where χ is any function of \vec{r} and t this will not change \vec{B} ($\vec{\nabla} \times (\vec{\nabla} \cdot \vec{B}) = 0$). It will change \vec{E} by $\left(-\frac{\partial}{\partial t} \vec{\nabla} \chi \right)$, but we can change φ to $\varphi' = \varphi - (\partial \chi / \partial t)$. Then \vec{E} and \vec{B} will both be unchanged. This property of changing representation (gauge) without changing \vec{E} and \vec{B} is **gauge invariance**. We can define a gauge transformation with

$$\vec{A}'(\vec{r}, t) = \vec{A}(\vec{r}, t) + \vec{\nabla} \cdot \chi(\vec{r}, t) \quad (7.6.23)$$

$$\varphi'(\vec{r}, t) = \varphi(\vec{r}, t) - \frac{\partial}{\partial t} \chi(\vec{r}, t) \quad (7.6.24)$$

Up to this point, \vec{A}' and φ' are undetermined. Let's choose a χ such that:

$$\vec{\nabla} \cdot \vec{A} + \epsilon_0 \mu_0 \frac{\partial \varphi}{\partial t} = 0 \quad (7.6.25)$$

which is known as the **Lorentz condition**. Then from Equation 7.6.19

$$-\vec{\nabla}^2 \vec{A} + \epsilon_0 \mu_0 \frac{\partial^2 \vec{A}}{\partial t^2} = \mu_0 \vec{J} \quad (7.6.26)$$

The right hand side of this equation can be set to zero when no currents are present. From Equation 7.6.22 we have:

$$\epsilon_0 \mu_0 \frac{\partial^2 \varphi}{\partial t^2} - \nabla^2 \varphi = \frac{\rho}{\epsilon_0} \quad (7.6.27)$$

Equations 7.6.26 and 7.6.27 are wave equations for \bar{A} and φ . Within the Lorentz gauge, we can still arbitrarily add another χ ; it must only satisfy Equation 7.6.25. If we substitute Equations 7.6.23 and 7.6.24 into Equation 7.6.27, we see

$$\nabla^2 \chi - \epsilon_0 \mu_0 \frac{\partial^2 \chi}{\partial t^2} = 0 \quad (7.6.28)$$

So we can make further choices/constraints on \bar{A} and φ as long as it obeys Equation 7.6.28. We now choose $\varphi = 0$, the **Coulomb gauge**, and from Equation 7.6.25 we see

$$\bar{\nabla} \cdot \bar{A} = 0 \quad (7.6.29)$$

So the wave equation for our vector potential when the field is far currents ($J = 0$) is

$$-\bar{\nabla}^2 \bar{A} + \epsilon_0 \mu_0 \frac{\partial^2 \bar{A}}{\partial t^2} = 0 \quad (7.6.30)$$

The solutions to this equation are plane waves:

$$\bar{A} = \bar{A}_0 \sin(\omega t - \bar{k} \cdot \bar{r} + \alpha) \quad (7.6.31)$$

where α is a phase. \bar{k} is the wave vector which points along the direction of propagation and has a magnitude

$$k^2 = \omega^2 \mu_0 \epsilon_0 = \omega^2 / c^2 \quad (7.6.32)$$

Since $\bar{\nabla} \cdot \bar{A} = 0$ (Equation 7.6.29), then

$$-\bar{k} \cdot \bar{A}_0 \cos(\omega t - \bar{k} \cdot \bar{r} + \alpha) = 0 \quad (7.6.33)$$

and

$$\bar{k} \cdot \bar{A}_0 = 0 \quad (7.6.34)$$

So the direction of the vector potential is perpendicular to the direction of wave propagation ($\bar{k} \perp \bar{A}_0$). From Equations 7.6.17 and 7.6.18 we see that for $\varphi = 0$:

$$\bar{E} = -\frac{\partial \bar{A}}{\partial t} \quad (7.6.35)$$

$$= -\omega \bar{A}_0 \cos(\omega t - \bar{k} \cdot \bar{r} + \alpha) \quad (7.6.36)$$

$$\bar{B} = \bar{\nabla} \times \bar{A} \quad (7.6.37)$$

$$= -(\bar{k} \times \bar{A}_0) \cos(\omega t - \bar{k} \cdot \bar{r} + \alpha) \quad (7.6.38)$$

Here the electric field is parallel with the vector potential, and the magnetic field is perpendicular to the electric field and the direction of propagation ($\bar{k} \perp \bar{E} \perp \bar{B}$). The Poynting vector describing the direction of energy propagation is

$$\bar{S} = \epsilon_0 c^2 (\bar{E} \times \bar{B}) \quad (7.6.39)$$

and its average value, the intensity, is

$$I = \langle S \rangle = \frac{1}{2} \epsilon_0 c E_0^2. \quad (7.6.40)$$

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