

10.2: Solving the Diffusion Equation

Solutions to the diffusion equation, such as eq. (10.1.5) and (10.1.6), are commonly solved with the use of Fourier transforms. If we define the transformation from real space to reciprocal space as

$$\tilde{C}(k, t) = \int_{-\infty}^{\infty} C(x) e^{ikx} dx$$

one can express the diffusion equation in 1D as

$$\frac{d\tilde{C}(k, t)}{dt} = -Dk^2 \tilde{C}(k, t) \quad (10.2.1)$$

[More generally one finds that the Fourier transform of a linear differential equation in x can be expressed in polynomial form: $\mathcal{F}(\partial^n f / \partial x^n) = (ik)^n \tilde{f}(k)$. This manipulation converts a partial differential equation into an ordinary one, which has the straightforward solution $\tilde{C}(k, t) = \tilde{C}(k, 0) \exp(-Dk^2 t)$. We do need to express the boundary conditions in reciprocal space, but then, this solution can be transformed back to obtain the real space solution using $C(x, t) = (2\pi)^{-1} \int_{-\infty}^{\infty} \tilde{C}(k, t) e^{-ikx} dk$.

Since eq. (10.2.1) is a linear differential equation, sums of solutions to the diffusion equation are also solutions. We can use this superposition principle to solve problems for complex initial conditions. Similarly, when the diffusion constant is independent of x and t , the general solution to the diffusion equation can also be expressed as a Fourier series. If we separate the time and space variables, so that the form of the solution is $C(x, t) = X(x)T(t)$ we find that we can write

$$\frac{1}{T} \frac{\partial T}{\partial t} = \frac{1}{X} \frac{\partial^2 X}{\partial x^2} = -\alpha^2$$

Where α is a constant. Then $T = e^{-\alpha^2 Dt}$ and $X = A \cos \alpha x + B \sin \alpha x$. This leads to the general form:

$$C(x, t) = \sum_{n=0}^{\infty} (A_n \cos \alpha_n x + B_n \sin \alpha_n x) e^{-\alpha_n^2 Dt} \quad (10.2.2)$$

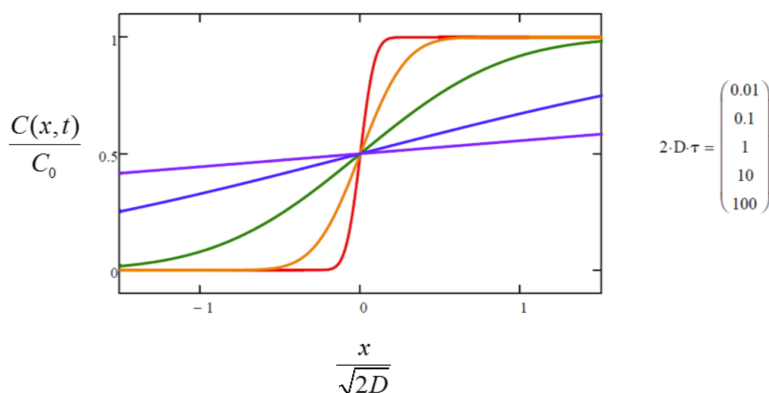
Here A_n and B_n are constants determined by the boundary conditions.

Examples

Diffusion across boundary

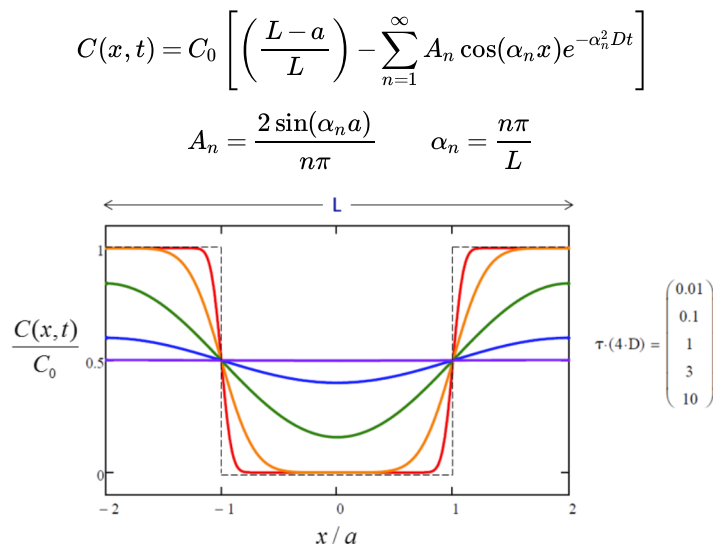
At time $t = 0$, the concentration is uniform at a value C_0 for $x \geq 0$, and zero for $x < 0$, similar to removing a barrier between two homogeneous media. Using the superposition principle, the solution is obtained by integrating the point source solution, eq. (10.1.5), over all initial point sources $\delta(x - x_0)$ such that $x_0 = 0 \rightarrow \infty$. Defining $y^2 = (x - x_0)^2 / 4Dt$,

$$C(x, t) = \frac{C_0}{\sqrt{\pi}} \int_0^{\infty} \frac{(x - x_0)}{\sqrt{4Dt}} dy e^{-y^2} = \frac{C_0}{2} \operatorname{erfc} \left(\frac{-(x - x_0)}{\sqrt{4Dt}} \right)$$



Diffusion into "hole"

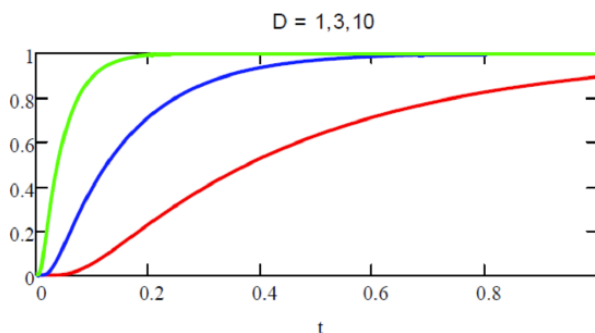
A concentration "hole" of width $2a$ is inserted into a box of length $2L$ with an initial concentration of C_0 . Let's take $L = 2a$. Concentration profile solution:



- **Fluorescence Recovery after Photobleaching (FRAP):** We can use this solution to describe the diffusion of fluorescently labeled molecules into a photobleached spot. Usually observe the increase of fluorescence with time from this spot. We integrate concentration over initial hole:

$$N_{FRAP}(t) = \int_{-a}^{+a} C(x, t) dx$$

$$= C_0 \left[\frac{2a}{L} (L-1) - L \sum_{n=1}^{\infty} A_n^2 e^{-\alpha_n^2 D t} \right]$$



Reflecting and Absorbing Boundary Conditions

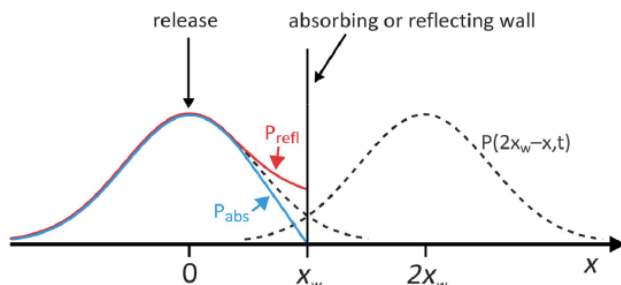
We will be interested in describing the time-dependent probability distribution for the case in which particles are released at $x=0$, subject to encountering an impenetrable wall at $x=x_w$, which can either absorb or reflect particles.

Consider the case of a reflecting wall, where the boundary condition requires that the flux at x_w is zero. This boundary condition and the resulting pile-up near the wall can be described by making use of the fact that any $P(x > x_w, t)$ can be reflected about x_w , which is equivalent to removing the boundary and adding a second source term to $P(x, t)$ for particles released at $x = 2x_w$

$$P_{refl}(x, t) = P(x, t) + P(2x_w - x, t) \quad (x < x_w)$$

This is also known as a wrap-around solution, since any component with any population from $P(x, t)$ that passes the position of the wall is reflected about x_w . Similarly, an absorbing wall, $P(x = x_w, t) = 0$, means that we remove any population that reached x_w , which is obtained from the difference of the two mirrored probability distributions:

$$P_{abs}(x, t) = P(x, t) - P(2x_w - x, t) \quad (x < x_w)$$



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