

### 1.3: The Microscopic Laws of Motion

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Consider a system of  $N$  classical particles. The particles are confined to a particular region of space by a "container" of volume  $V$ . The particles have a finite kinetic energy and are therefore in constant motion, driven by the forces they exert on each other (and any external forces which may be present). At a given instant in time  $t$ , the Cartesian positions of the particles are  $r_1(t), \dots, r_N(t)$ . The time evolution of the positions of the particles is then given by Newton's second law of motion:

$$m_i \ddot{r}_i = F_i(r_1, \dots, r_N)$$

where  $F_1, \dots, F_N$  are the forces on each of the  $N$  particles due to all the other particles in the system. The notation  $\ddot{r}_i = \frac{d^2 r_i}{dt^2}$ .

$N$  Newton's equations of motion constitute a set of  $3N$  coupled second order differential equations. In order to solve these, it is necessary to specify a set of appropriate initial conditions on the coordinates and their first time derivatives,  $\{r_1(0), \dots, r_N(0), \dot{r}_1(0), \dots, \dot{r}_N(0)\}$ . Then, the solution of Newton's equations gives the complete set of coordinates and velocities for all time  $t$ .

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