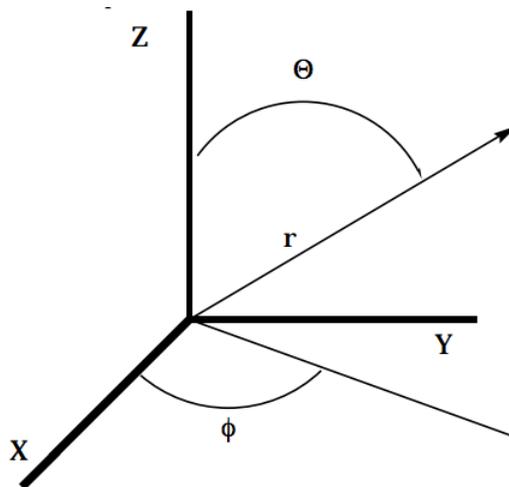


22.1.5: v. Review Exercise Solutions

Q1

The general relationships are as follows:



$$\begin{aligned}
 x &= r \sin \theta \cos \phi & r^2 &= x^2 + y^2 + z^2 \\
 y &= r \sin \theta \sin \phi & \sin \theta &= \frac{\sqrt{x^2 + y^2}}{\sqrt{x^2 + y^2 + z^2}} \\
 z &= r \cos \theta & \cos \theta &= \frac{z}{\sqrt{x^2 + y^2 + z^2}} \\
 & & \tan \phi &= \frac{y}{x}
 \end{aligned}$$

a.

$$\begin{aligned}
 3x + y - 4z &= 12 \\
 3(r \sin \theta \cos \phi) + \sin \theta \sin \phi - 4(r \cos \theta) &= 12 \\
 r(3 \sin \theta \cos \phi + \sin \theta \sin \phi - 4 \cos \theta) &= 12
 \end{aligned}$$

b.

$$\begin{aligned}
 x &= r \cos \phi & r^2 &= x^2 + y^2 \\
 y &= r \sin \phi & \tan \phi &= \frac{y}{x} \\
 z &= z & y^2 + z^2 &= 9 \\
 & & r^2 \sin^2 \phi + z^2 &= 9
 \end{aligned}$$

c.

$$\begin{aligned}
 r &= 2 \sin \theta \cos \phi \\
 r &= 2 \left(\frac{x}{r} \right) \\
 r^2 &= 2x \\
 x^2 + y^2 + z^2 &= 2x \\
 x^2 - 2x + y^2 + z^2 &= 0 \\
 x^2 - 2x + 1 + y^2 + z^2 &= 1 \\
 (x - 1)^2 + y^2 + z^2 &= 1
 \end{aligned}$$

Q2

a.

$$\begin{aligned}
 9x + 16y \frac{\partial y}{\partial x} &= 0 \\
 16y dy &= -9x dx \\
 \frac{16}{2} y^2 &= -\frac{9}{2} x^2 + c \\
 16y^2 &= -9x^2 + c' \\
 \frac{y^2}{9} + \frac{x^2}{16} &= c'' \text{ (general equation for an ellipse)}
 \end{aligned}$$

b.

$$\begin{aligned}
 2y + \frac{\partial y}{\partial x} + 6 &= 0 \\
 2y + 6 &= -\frac{dy}{dx} \\
 -2dx &= -\frac{dy}{2dx} \\
 -2dx &= \frac{dy}{y+3} \\
 -2x &= \ln(y+3) + c \\
 c'e^{-2x} &= y+3 \\
 y &= c'e^{-2x} - 3
 \end{aligned}$$

Q3

a. First determine the eigenvalues:

$$\begin{aligned}
 \det \begin{bmatrix} -1-\lambda & 2 \\ 2 & 2-\lambda \end{bmatrix} &= 0 \\
 (-1-\lambda)(2-\lambda) - 2^2 &= 0 \\
 -2 + \lambda - 2\lambda + \lambda^2 - 4 &= 0 \\
 \lambda^2 - \lambda - 6 &= 0 \\
 (\lambda - 3)(\lambda + 2) &= 0 \\
 \lambda = 3 \text{ or } \lambda = -2.
 \end{aligned}$$

Next, determine the eigenvectors. First, the eigenvector associated with eigenvalue -2:

$$\begin{aligned}
 \begin{bmatrix} -1 & 2 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} C_{11} \\ C_{21} \end{bmatrix} &= -2 \begin{bmatrix} C_{11} \\ C_{21} \end{bmatrix} \\
 -C_{11} + 2C_{21} &= -2C_{11} \\
 C_{11} &= -2C_{21}
 \end{aligned}$$

(Note: The second row offers no new information, e.g. $2C_{11} + 2C_{21} = -2C_{21}$)

$$C_{11}^2 + C_{21}^2 = 1 \text{ (from normalization)}$$

$$(-2C_{21})^2 + C_{21}^2 = 1$$

$$4C_{21}^2 + C_{21}^2 = 1$$

$$5C_{21}^2 = 1$$

$$C_{21}^2 = 0.2$$

$$C_{21} = \sqrt{0.2}$$

(again the second row offers no new information)

$$C_{12}^2 + C_{22}^2 = 1$$

$$0.25C_{22}^2 + C_{22}^2 = 1$$

$$1.25C_{22}^2 = 1$$

$$C_{22}^2 = 0.8$$

$$C_{22} = \sqrt{0.8} = 2\sqrt{0.2}, \text{ and therefore } C_{12} = \sqrt{0.2}.$$

Therefore the eigenvector matrix becomes:

$$\begin{bmatrix} -2\sqrt{0.2} & \sqrt{0.2} \\ \sqrt{0.2} & 2\sqrt{0.2} \end{bmatrix}$$

b. First determine the eigenvalues:

$$\det \begin{bmatrix} -2-\lambda & 0 & 0 \\ 0 & -1-\lambda & 2 \\ 0 & 2 & 2-\lambda \end{bmatrix} = 0$$

$$\det[-2-\lambda] \det \begin{bmatrix} -1-\lambda & 2 \\ 2 & 2-\lambda \end{bmatrix} = 0$$

From 3a, the solutions then become -2, -2, and 3. Next, determine the eigenvectors. First the eigenvector associated with eigenvalue 3 (the third root):

$$\begin{bmatrix} -2 & 0 & 0 \\ 0 & -1 & 2 \\ 0 & 2 & 2 \end{bmatrix} \begin{bmatrix} C_{11} \\ C_{21} \\ C_{31} \end{bmatrix} = 3 \begin{bmatrix} C_{11} \\ C_{21} \\ C_{31} \end{bmatrix}$$

$$-2C_{13} = 3C_{13} \text{ (row one)}$$

$$C_{13} = 0$$

$$-C_{23} + 2C_{33} = 3C_{23} \text{ (row two)}$$

$$2C_{33} = 2C_{23}$$

$$C_{33} = 2C_{23} \text{ (again the third row offers no new information)}$$

$$C_{13}^2 + C_{23}^2 + C_{33}^2 = 1 \text{ (from normalization)}$$

$$0 + C_{23}^2 + (2C_{23})^2 = 1$$

$$5C_{23}^2 = 1$$

$$C_{23} = \sqrt{0.2}, \text{ and therefore } C_{33} = \sqrt{0.2}.$$

Next, find the pair of eigenvectors associated with the degenerate eigenvalue of -2. First, root one eigenvector one:

$$\begin{aligned}
 -2C_{11} &= -2C_{11} \text{ (no new information from row one)} \\
 -C_{21} + 2C_{31} &= -2C_{21} \text{ (row two)} \\
 C_{21} &= -2C_{31} \text{ (again the third row offers no new information)} \\
 C_{11}^2 + C_{21}^2 + C_{31}^2 &= 1 \text{ (from normalization)} \\
 C_{11}^2 + (-2C_{31})^2 + C_{31}^2 &= 1 \\
 C_{11}^2 + 5C_{31}^2 &= 1 \\
 C_{11} &= \sqrt{1 - 5C_{31}^2}
 \end{aligned}$$

Note: There are now two equations with three unknowns. Second, root two eigenvector two:

$$\begin{aligned}
 -2C_{12} &= -2C_{12} \text{ (no new information from row one)} \\
 -C_{21} + 2C_{31} &= -2C_{21} \text{ (row two)} \\
 C_{21} &= -2C_{31} \text{ (again the third row offers no new information)} \\
 C_{11}^2 + C_{21}^2 + C_{31}^2 &= 1 \text{ (from normalization)} \\
 C_{12}^2 + (-2C_{32})^2 + C_{32}^2 &= 1 \\
 C_{12}^2 + 5C_{32}^2 &= 1 \\
 C_{12} &= \sqrt{1 - 5C_{32}^2}
 \end{aligned}$$

Note: Again there are now two equations with three unknowns.

$$C_{11}C_{12} + C_{21}C_{22} + C_{31}C_{32} = 0 \text{ (from orthogonalization)}$$

Now there are five equations with six unknowns.

$$\begin{aligned}
 &\text{Arbitrarily choose } C_{11} = 0 \\
 C_{11} = 0 &= \sqrt{1 - 5C_{31}^2} \\
 5C_{31}^2 &= 1 \\
 C_{31} &= \sqrt{0.2} \\
 C_{21} &= -2\sqrt{0.2} \\
 C_{11}C_{12} + C_{21}C_{22} + C_{31}C_{32} &= 0 \text{ (from orthogonalization)} \\
 0 + -2\sqrt{0.2}(-2C_{32}) + \sqrt{0.2}C_{32} &= 0 \\
 5C_{32} &= 0 \\
 C_{32} = 0, C_{22} = 0, \text{ and } C_{12} &= 1
 \end{aligned}$$

Therefore the eigenvector matrix becomes:

$$\begin{bmatrix}
 0 & 1 & 0 \\
 -2\sqrt{0.2} & 0 & \sqrt{0.2} \\
 \sqrt{0.2} & 0 & 2\sqrt{0.2}
 \end{bmatrix}$$

Q4

Show: $\langle \phi_1 | \phi_1 \rangle = 1$, $\langle \phi_2 | \phi_2 \rangle = 1$, and $\langle \phi_1 | \phi_2 \rangle = 0$

$$\begin{aligned}
 \langle \phi_1 | \phi_1 \rangle &\stackrel{?}{=} 1 \\
 (-2\sqrt{0.2})^2 + (\sqrt{0.2})^2 &\stackrel{?}{=} 1 \\
 4(0.2) + 0.2 &\stackrel{?}{=} 1 \\
 0.8 + 0.2 &\stackrel{?}{=} 1 \\
 1 &= 1 \\
 \langle \phi_2 | \phi_2 \rangle &\stackrel{?}{=} 1 \\
 (\sqrt{0.2})^2 + (2\sqrt{0.2})^2 &\stackrel{?}{=} 1 \\
 0.2 + 4(0.2) &\stackrel{?}{=} 1 \\
 0.2 + 0.8 &\stackrel{?}{=} 1 \\
 1 &= 1 \\
 \langle \phi_1 | \phi_2 \rangle = \langle \phi_2 | \phi_1 \rangle &\stackrel{?}{=} 0 \\
 -2\sqrt{0.2}\sqrt{0.2}\sqrt{0.2}2\sqrt{0.2} &\stackrel{?}{=} 0 \\
 -2(0.2) + 2(0.2) &\stackrel{?}{=} 0 \\
 -0.4 + 0.4 &\stackrel{?}{=} 0 \\
 0 &= 0
 \end{aligned}$$

Q5

Show (for the degenerate eigenvalue; $\lambda = -2$): $\langle \phi_2 | \phi_2 \rangle = 1$, $\langle \phi_2 | \phi_1 \rangle = 1$, and $\langle \phi_1 | e\phi \rangle = 0$

$$\begin{aligned}
 \langle \phi_1 | \phi_1 \rangle &\stackrel{?}{=} 1 \\
 0 + (-2\sqrt{0.2})^2 + (\sqrt{0.2})^2 &\stackrel{?}{=} 1 \\
 4(0.2) + 0.2 &\stackrel{?}{=} 1 \\
 0.8 + 0.2 &\stackrel{?}{=} 1 \\
 1 &= 1 \\
 \langle \phi_1 | \phi_2 \rangle &\stackrel{?}{=} 1 \\
 1^2 + 0 + 0 &\stackrel{?}{=} 1 \\
 1 &= 1 \\
 \langle \phi_1 | \phi_2 \rangle = \langle \phi_2 | \phi_1 \rangle &\stackrel{?}{=} 0 \\
 (0)(1) + (-2\sqrt{0.2})(0) + (\sqrt{0.2})(0) &\stackrel{?}{=} 0
 \end{aligned}$$

Q6

Suppose the solution is of the form $x(t) = e^{\alpha t}$, with α unknown. Inserting this trial solution into the differential equation results in the following:

$$\begin{aligned}
 \frac{d^2}{dt^2} e^{\alpha t} + k^2 e^{\alpha t} &= 0 \\
 \alpha^2 e^{\alpha t} + k^2 e^{\alpha t} &= 0 \\
 (\alpha^2 + k^2) x(t) &= 0 \\
 (\alpha^2 + k^2) &= 0 \\
 \alpha^2 &= -k^2 \\
 \alpha &= \sqrt{-k^2} \\
 \alpha &= \pm ik
 \end{aligned}$$

\therefore Solutions are of the form e^{-ikt} , e^{ikt} , or a combination of both: $x(t) = C_1 e^{ikt} + C_2 e^{-ikt}$.

Euler's formula also states that: $e^{+i\theta} = \cos\theta + i\sin\theta$, so the previous equation for $x(t)$ can also be written as:

$$\begin{aligned}x(t) &= C_1 [\cos(kt) + i\sin(kt)] + C_2 [\cos(kt) - i\sin(kt)] \\x(t) &= (C_1 + C_2) \cos(kt) + (C_1 - C_2) i\sin(kt), \text{ or alternatively} \\x(t) &= C_3 \cos(kt) + C_4 \sin(kt).\end{aligned}$$

We can determine these coefficients by making use of the "boundary conditions".

$$\begin{aligned}\text{at } t = 0, x(0) &= L \\x(0) &= C_3 \cos(0) + C_4 \sin(0) = L \\C_3 &= L \\ \text{at } t = 0, \frac{dx(0)}{dt} &= 0 \\ \frac{d}{dt} x(t) &= \frac{d}{dt} (C_3 \cos(kt) + C_4 \sin(kt)) \\ \frac{d}{dt} x(t) &= -C_3 k \sin(kt) + C_4 k \cos(kt) \\ \frac{d}{dt} x(0) = 0 &= -C_3 k \sin(0) + C_4 k \cos(0) \\ C_4 k &= 0 \\ C_4 &= 0\end{aligned}$$

∴ The solution is of the form: $x(t) = L \cos(kt)$

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