

## Module 4 - Summary

### Summary Notes Module 4

- Any amplitude distribution can be expressed as a sum of plane waves, i.e.,  $\exp[j2\pi(ux + vy)]$ . Compared to the mathematical expression of a plane wave in Module 2,  $\exp[j(k_x x + k_y y)]$ , then  $k_x = 2\pi u = \frac{2\pi}{\lambda} \sin \theta_x$  and  $k_y = 2\pi v = \frac{2\pi}{\lambda} \sin \theta_y$ . This means that the angle of the plane waves along the x- and y-direction can be estimated by  $\theta_x = \sin^{-1}(\lambda u)$  and  $\theta_y = \sin^{-1}(\lambda v)$ .
- An imaging system must be a linear shift-invariant system. Consider that an imaging system is represented by a **S** operator.

$$\begin{array}{ccc} \text{input} & \left[ \begin{array}{c} \text{Imaging system} \\ \mathbf{S}\{\cdot\} \end{array} \right] & \text{output} \\ f(x, y) & & g(x, y) \end{array} \quad \longrightarrow \quad g(x, y) = \mathbf{S}\{f(x, y)\}$$

A system is linear if the output is equal to the sum of the individual outputs.

$$\begin{array}{ccc} \text{input} & \left[ \begin{array}{c} \text{Imaging system} \\ \mathbf{S}\{\cdot\} \end{array} \right] & \text{output} \\ f_1(x, y) & & g_1(x, y) = \mathbf{S}\{f_1(x, y)\} \\ \\ \text{input} & \left[ \begin{array}{c} \text{Imaging system} \\ \mathbf{S}\{\cdot\} \end{array} \right] & \text{output} \\ f_2(x, y) & & g_2(x, y) = \mathbf{S}\{f_2(x, y)\} \\ \\ \text{input} & \left[ \begin{array}{c} \text{Imaging system} \\ \mathbf{S}\{\cdot\} \end{array} \right] & \text{output} \\ f_3(x, y) = & & g_3(x, y) = \mathbf{S}\{f_3(x, y)\} \\ = \alpha f_1(x, y) + \beta f_2(x, y) & & = \mathbf{S}\{\alpha f_1(x, y) + \beta f_2(x, y)\} \\ & & = \alpha g_1(x, y) + \beta g_2(x, y) \end{array}$$

A system is shift-invariant if the output of a displaced input signal is the same function but displaced by the same amount.

$$\begin{array}{ccc} \text{input} & \left[ \begin{array}{c} \text{Imaging system} \\ \mathbf{S}\{\cdot\} \end{array} \right] & \text{output} \\ f(x, y) & & g(x, y) = \mathbf{S}\{f(x, y)\} \\ \\ \text{input} & \left[ \begin{array}{c} \text{Imaging system} \\ \mathbf{S}\{\cdot\} \end{array} \right] & \text{output} \\ f(x - \alpha, y - \beta) & & g'(x, y) = \mathbf{S}\{f(x - \alpha, y - \beta)\} = \\ & & = g(x - \alpha, y - \beta) \end{array}$$

Only when the optical system is linear space-invariant (LSI), the output signal,  $g(x, y)$ , can be expressed as the two-dimensional (2D) convolution ( $\otimes_2$ ) between the input signal,  $f(x, y)$ , and the impulse response of the system,  $h(x, y)$ :

$$g(x, y) = f(x, y) \otimes_2 h(x, y). \quad (1)$$

In the Fourier domain, the spectrum of the output signal,  $G(u, v)$ , is the product between the spectrum of the input signal,  $F(u, v)$ , and the optical transfer function,  $H(u, v)$ :

$$G(u, v) = F(u, v)H(u, v). \quad (2)$$

This means that the transfer function  $H(u, v)$  is the 2D Fourier transform of the impulse response,  $h(x, y)$ :

$$H(u, v) = \text{FT}[h(x, y)]. \quad (3)$$

• Free-space propagator under the Fresnel approximation

$$h(x, y) = \frac{e^{jkz}}{j\lambda z} \exp\left[j\frac{k}{2z}(x^2 + y^2)\right], \quad (4)$$

and

$$H(u, v) = \frac{e^{jkz}}{j\lambda z} \exp[-j\pi\lambda z(u^2 + v^2)]. \quad (5)$$

Condition of the Fresnel region:

$$N_F \frac{\theta_m^2}{4} \ll 1, \quad (6)$$

where  $N_F = \frac{a^2}{\lambda z}$  is the Fresnel number and  $\theta_m = \frac{a}{z}$  is the maximum aperture angle.

• Free-space propagator under the Fraunhofer approximation ( $z \gg$ )

$$g(x, y) = f(x, y) \otimes_2 h(x, y) = F\left(\frac{x}{\lambda z}, \frac{y}{\lambda z}\right) = F\left(\frac{x}{M}, \frac{y}{M}\right), \quad (7)$$

where  $M$  is the magnification factor.

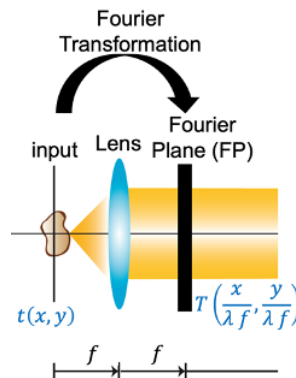
For  $z \gg$ , the amplitude distribution (also known as the diffraction pattern) of an object transmittance  $f(x, y)$  is a scaled version of its Fourier Transform under Fraunhofer approximation.

Condition of the Fraunhofer region:

$$z \gg \frac{b_{\text{input}}^2}{\lambda} \quad \text{and} \quad z \gg \frac{a_{\text{output}}^2}{\lambda}, \quad (8)$$

where  $b_{\text{input}}$  is the maximum lateral extent in the input plane and  $a_{\text{output}}$  is the maximum lateral extent in the output plane.

• Converging and diverging (i.e., optical) lenses make Fourier transforms.



Consider a converging lens. If an object with amplitude transmittance  $t(x, y)$  is placed at the front focal plane of a lens (i.e., the distance between the object/input and lens planes is equal to the lens' focal length,  $f$ ), a scaled replica of the Fourier transform of the object transmittance is found at its back focal plane:

$$T\left(\frac{x}{\lambda f}, \frac{y}{\lambda f}\right). \quad (9)$$

- Calculation of the complex amplitude distribution of an arbitrary optical system with an input transmittance  $t(x, y)$ . The arbitrary optical system is represented by its ABCD matrix.

$$\text{input } t(x, y) \begin{bmatrix} \text{Optical system} \\ [A & B \\ C & D] \end{bmatrix} \text{output } u(x, y)$$

If  $B = 0$ , the complex amplitude distribution at the output plane is the product of a quadratic phase wavefront and a scaled replica of the object transmittance:

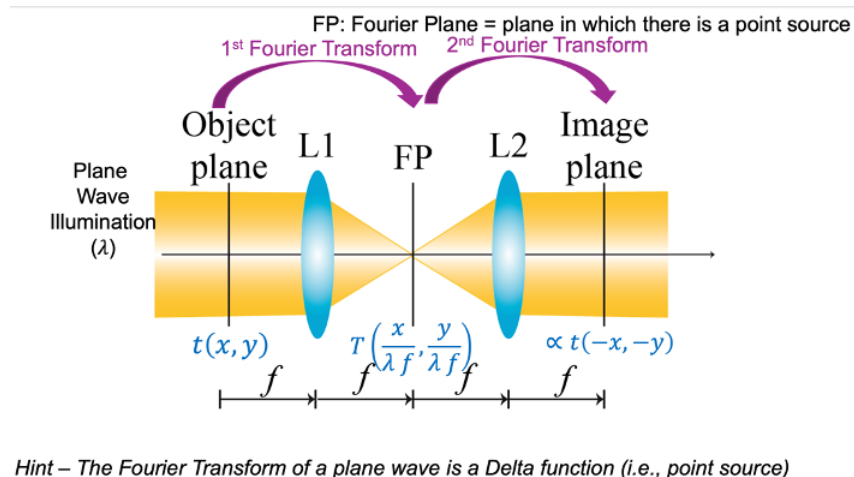
$$u(x, y) = e^{jkL_0/A} \exp\left[j\frac{kC}{2A}(x^2 + y^2)\right] t\left(\frac{x}{A}, \frac{y}{A}\right), \quad (10)$$

where  $L_0$  is the geometrical distance between the input and output planes and  $k = \frac{2\pi}{\lambda}$  is the wave number.

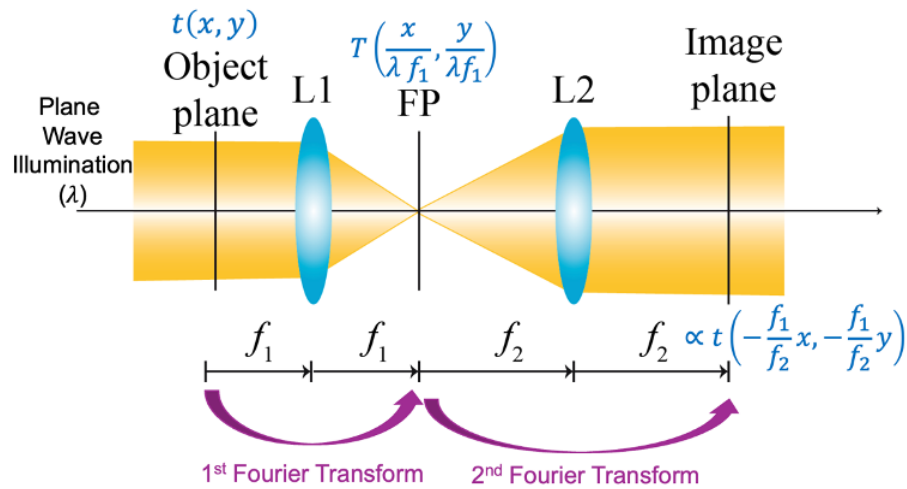
Else, if  $B \neq 0$ , the complex amplitude distribution at the output plane becomes:

$$u(x, y) = \frac{e^{jkL_0}}{j\lambda B} \exp\left[j\frac{kD}{2B}(x^2 + y^2)\right] \int_{-\infty}^{\infty} t(x_0, y_0) \exp\left[j\frac{kA}{2B}(x_0^2 + y_0^2)\right] \exp\left[-j\frac{2\pi}{\lambda B}(xx_0 + yy_0)\right] dx_0 dy_0. \quad (11)$$

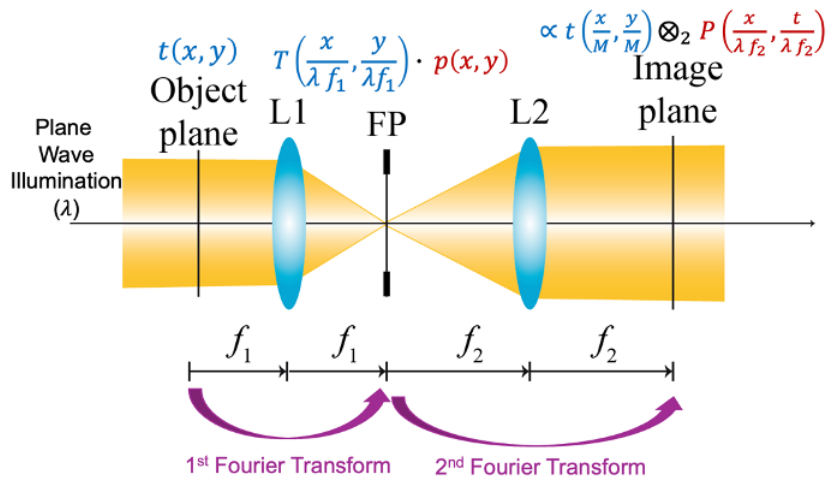
- 4f imaging system if both lenses have the same focal length



- 4f imaging system if both lenses have different focal lengths



- Spatial filtering in a 4f imaging system by inserting a pupil with transmittance  $p(x, y)$  at the Fourier plane of a 4f system. The pupil filters out some object frequencies.



Thus, the complex amplitude at the image plane (i.e., back focal plane of the  $L_2$  lens) is:

$$u(x, y) = \frac{1}{M^2} t\left(\frac{x}{M}, \frac{y}{M}\right) \otimes_2 P\left(\frac{x}{\lambda f_2}, \frac{y}{\lambda f_2}\right) = \frac{1}{M^2} t\left(\frac{x}{M}, \frac{y}{M}\right) \otimes_2 h(x, y), \quad (12)$$

where  $M = -\frac{f_2}{f_1}$  is the lateral magnification,  $\otimes_2$  is the 2D convolution operator, and  $P(u, v)$  is the 2D Fourier transform of the pupil transmittance. Based on the equation, the impulse response of the 4f imaging system is a scaled replica of the pupil's Fourier transform,  $h(x, y) = P\left(\frac{x}{\lambda f_2}, \frac{y}{\lambda f_2}\right)$ . Therefore, the transfer function is a scaled replica of the pupil's transmittance:

$$H(u, v) = \text{FT}[h(x, y)] = p\left(-\frac{\lambda f_2 u}{f_1}, -\frac{\lambda f_2 v}{f_1}\right). \quad (13)$$

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