

17.2: Two Coupled Pendulums

We'll take two equal pendulums, coupled by a light spring. We take the spring restoring force to be directly proportional to the angular difference between the pendulums. (This turns out to be a good approximation.)

For small angles of oscillation, we take the Lagrangian to be

$$L = \frac{1}{2}m\ell^2\dot{\theta}_1^2 + \frac{1}{2}m\ell^2\dot{\theta}_2^2 - \frac{1}{2}mg\ell\theta_1^2 - \frac{1}{2}mg\ell\theta_2^2 - \frac{1}{2}C(\theta_1 - \theta_2)^2 \quad (17.2.1)$$

Denoting the single pendulum frequency by ω_0 , the equations of motion are (writing $\omega_0^2 = g/\ell$, $k = C/m\ell^2$, so $[k] = T^{-2}$)

$$\begin{aligned}\ddot{\theta}_1 &= -\omega_0^2\theta_1 - k(\theta_1 - \theta_2) \\ \ddot{\theta}_2 &= -\omega_0^2\theta_2 - k(\theta_2 - \theta_1)\end{aligned} \quad (17.2.2)$$

We look for a periodic solution, writing

$$\theta_1(t) = A_1 e^{i\omega t}, \quad \theta_2(t) = A_2 e^{i\omega t} \quad (17.2.3)$$

(The final physical angle solutions will be the real part.)

The equations become (in matrix notation):

$$\omega^2 \begin{pmatrix} A_1 \\ A_2 \end{pmatrix} = \begin{pmatrix} \omega_0^2 + k & -k \\ -k & \omega_0^2 + k \end{pmatrix} \begin{pmatrix} A_1 \\ A_2 \end{pmatrix} \quad (17.2.4)$$

Denoting the 2×2 matrix by \mathbf{M}

$$\mathbf{M}\vec{A} = \omega^2 \vec{A}, \quad \vec{A} = \begin{pmatrix} A_1 \\ A_2 \end{pmatrix} \quad (17.2.5)$$

This is an eigenvector equation, with ω^2 the eigenvalue, found by the standard procedure:

$$\det(\mathbf{M} - \omega^2 \mathbf{I}) = \begin{vmatrix} \omega_0^2 + k - \omega^2 & -k \\ -k & \omega_0^2 + k - \omega^2 \end{vmatrix} = 0 \quad (17.2.6)$$

Solving, $\omega^2 = \omega_0^2 + k \pm k$, that is

$$\omega^2 = \omega_0^2, \quad \omega^2 = \omega_0^2 + 2k \quad (17.2.7)$$

The corresponding eigenvectors are (1,1) and (1,-1).

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