

CHAPTER OVERVIEW

Model 4: The Rigid Body Model

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 - 01. Concepts and Principles
 - 02. Pure Rotation
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 - 04. Activities
- 03. Dynamics
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 - 02. Calculating the Rotational Inertia
 - 03. Applying Newton's Second Law in Translational and Rotational Form - I
 - 04. Applying Newton's Second Law in Translational and Rotational Form - II
 - 05. Applying Newton's Second Law to Rolling Motion
 - 06. Rotational Inertia of Common, Uniform Solids
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 - 02. Applying the Work-Energy Relation including Rotation - I
 - 03. Applying the Impulse-Momentum Relations (Linear and Angular) - I
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