

## 6.2: N Coupled Oscillators

The calculations of the previous section may be readily generalized to the case of an arbitrary number (say,  $N$ ) coupled harmonic oscillators, with an arbitrary type of coupling. It is evident that in this case Eq. (4) should be replaced with

$$L = \sum_{j=1}^N L_j + \sum_{j,j'=1}^N L_{jj'} \quad (6.2.1)$$

Moreover, we can generalize the above expression for the mixed terms  $L_{jj'}$ , taking into account their possible dependence not only on the generalized coordinates but also on the generalized velocities, in a bilinear form similar to Eq. (4). The resulting Lagrangian may be represented in a compact form,

$$L = \sum_{j,j'=1}^N \left( \frac{m_{ij'}}{2} \dot{q}_j \dot{q}_{j'} - \frac{\kappa_{ij'}}{2} q_j q_{j'} \right), \quad (6.2.2)$$

where the off-diagonal terms are index-symmetric:  $m_{jj'} = m_{j'j}$ ,  $\kappa_{jj'} = \kappa_{j'j}$ , and the factors  $1/2$  compensate the double counting of each term with  $j \neq j'$ , taking place at the summation over two independently running indices. One may argue that Eq. (16) is quite general if we still want to keep the equations of motion linear - as they always are if the oscillations are small enough.

Plugging Eq. (16) into the general form (2.19) of the Lagrange equation, we get  $N$  equations of motion of the system, one for each value of the index  $j' = 1, 2, \dots, N$ :

$$\sum_{j=1}^N (m_{ijj} \ddot{q}_j + \kappa_{jj'} q_j) = 0. \quad (6.2.3)$$

Just as in the previous section, let us look for a particular solution to this system in the form

$$q_j = c_j e^{\lambda t}. \quad (6.2.4)$$

As a result, we are getting a system of  $N$  linear, homogeneous algebraic equations,

$$\sum_{j=1}^N (m_{ijj} \lambda^2 + \kappa_{jj'}) c_j = 0, \quad (6.2.5)$$

for the set of  $N$  distribution coefficients  $c_j$ . The condition that this system is self-consistent is that the determinant of its matrix equals zero:

$$\text{Det}(m_{ijj} \lambda^2 + \kappa_{jj'}) = 0. \quad (6.2.6)$$

This characteristic equation is an algebraic equation of degree  $N$  for  $\lambda^2$ , and so has  $N$  roots  $(\lambda^2)_n$ . For any Hamiltonian system with stable equilibrium, the matrices  $m_{ij}$  and  $\kappa_{ij}$  ensure that all these roots are real and negative. As a result, the general solution to Eq. (17) is the sum of  $2N$  terms proportional to  $\exp\{\pm i\omega_n t\}$ ,  $n = 1, 2, \dots, N$ , where all  $N$  eigenfrequencies  $\omega_n$  are real.

Plugging each of these  $2N$  values of  $\lambda = \pm i\omega_n$  back into a particular set of linear equations (17), one can find the corresponding set of distribution coefficients  $c_{j\pm}$ . Generally, the coefficients are complex, but to keep  $q_j(t)$  real, the coefficients  $c_{j+}$  corresponding to  $\lambda = +i\omega_n$ , and  $c_j$  - corresponding to  $\lambda = -i\omega_n$  have to be complex-conjugate of each other. Since the sets of the distribution coefficients may be different for each  $\lambda_n$ , they should be marked with two indices,  $j$  and  $n$ . Thus, at general initial conditions, the time evolution of the  $j^{\text{th}}$  coordinate may be represented as

$$q_j = \frac{1}{2} \sum_{n=1}^N (c_{jn} \exp\{+i\omega_n t\} + c_{jn}^* \exp\{-i\omega_n t\}) \equiv \text{Re} \sum_{n=1}^N c_{jn} \exp\{i\omega_n t\} \quad (6.2.7)$$

This formula shows very clearly again the physical sense of the distribution coefficients  $c_{jn}$ : a set of these coefficients, with different values of index  $j$  but the same  $n$ , gives the complex amplitudes of oscillations of the coordinates for the special initial conditions that ensure purely sinusoidal motion of all the system, with frequency  $\omega_n$ .

The calculation of the eigenfrequencies and distribution coefficients of a particular coupled system with many degrees of freedom from Eqs. (19)-(20) is a task that frequently may be only done numerically.<sup>4</sup> Let us discuss just two particular but very important cases. First, let all the coupling coefficients be small in the following sense:  $|m_{jj'}| \ll m_j \equiv m_{jj}$  and  $|\kappa_{ij'}| \ll \kappa_j \equiv \kappa_{jj}$ , for all  $j \neq j'$ , and all partial frequencies  $\Omega_j \equiv (\kappa_j/m_j)^{1/2}$  be not too close to each other:

$$\frac{|\Omega_j^2 - \Omega_{j'}^2|}{\Omega_j^2} \gg \frac{|\kappa_{jj'}|}{\kappa_j}, \frac{|m_{jj'}|}{m_j}, \quad \text{for all } j \neq j'. \quad (6.2.8)$$

(Such situation frequently happens if parameters of the system are "random" in the sense that they do not follow any special, simple rule - for example, resulting from some simple symmetry of the system.) Results of the previous section imply that in this case, the coupling does not produce a noticeable change of oscillation frequencies:  $\{\omega_n\} \approx \{\Omega_j\}$ . In this situation, oscillations at each eigenfrequency are heavily concentrated in one degree of freedom, i.e. in each set of the distribution coefficients  $c_{jn}$  (for a given  $n$ ), one coefficient's magnitude is much larger than all others.

Now let the conditions (22) be valid for all but one pair of partial frequencies, say  $\Omega_1$  and  $\Omega_2$ , while these two frequencies are so close that coupling of the corresponding partial oscillators becomes essential. In this case, the approximation  $\{\omega_n\} \approx \{\Omega_j\}$  is still valid for all other degrees of freedom, and the corresponding terms may be neglected in Eqs. (19) for  $j = 1$  and  $2$ . As a result, we return to Eqs. (7) (perhaps generalized for velocity coupling) and hence to the anticrossing diagram (Figure 2) discussed in the previous section. As a result, an extended change of only one partial frequency (say,  $\Omega_1$ ) of a weakly coupled system produces a sequence of eigenfrequency anticrossings - see Figure 3.

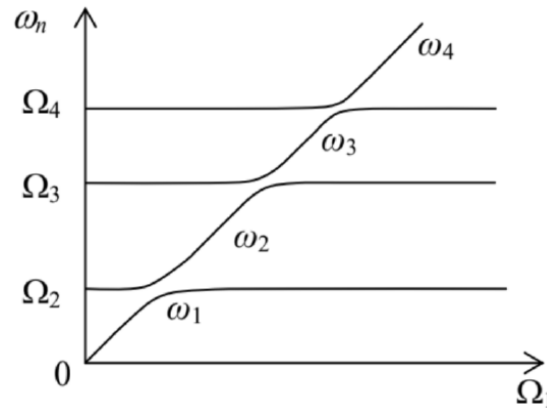


Figure 6.3. The level anticrossing in a system of  $N$  weakly coupled oscillators - schematically.

<sup>4</sup> Fortunately, very effective algorithms have been developed for this matrix diagonalization task - see, e.g., references in MA Sec. 16(iii)-(iv). For example, the popular MATLAB software package was initially created exactly for this purpose. ("MAT" in its name stands for "matrix" rather than "mathematics".)