

## 4.5: Force

### Learning Objectives

- Explain force and relativity

Force is a concept that is seldom needed in relativity, and that's why this section is optional.

### Four-force

By analogy with Newtonian mechanics, we define a relativistic force vector

$$F = m \cdot a \quad (4.5.1)$$

where  $a$  is the acceleration four-vector (section 3.5) and  $m$  is the mass of a particle that has that acceleration as a result of the force  $F$ . This is equivalent to

$$F = \frac{dp}{d\tau} \quad (4.5.2)$$

where  $p$  is the mass of the particle and  $\tau$  its proper time. Since the timelike part of  $p$  is the particle's mass-energy, the timelike component of the force is related to the power expended by the force. These definitions only work for massive particles, since for a massless particle we can't define  $a$  or  $\tau$ .  $F$  has been defined in terms of Lorentz invariants and four-vectors, and therefore it transforms as a god-fearing four-vector itself.

### The force measured by an observer

The trouble with all this is that  $F$  isn't what we actually measure when we measure a force, except if we happen to be in a frame of reference that momentarily coincides with the rest frame of the particle. As with velocity and acceleration (section 3.7), we have a four-vector that has simple, standard transformation properties, but a different  $F_o$ , which is what is actually measured by the observer  $o$ . It's defined as

$$F_o = \frac{dp}{dt} \quad (4.5.3)$$

with a  $dt$  in the denominator rather than a  $d\tau$ . In other words, it measures the rate of transfer of momentum according to the observer, whose time coordinate is  $t$ , not  $\tau$  — unless the observer happens to be moving along with the particle. Unlike the three-vectors  $v_o$  and  $a_o$ , whose timelike components are zero by definition according to observer  $o$ ,  $F_o$  usually has a nonvanishing timelike component, which is the rate of change of the particle's mass-energy, i.e., the power. We can refer to the spacelike part of  $F_o$  as the three-force.

The following two examples show that an object moving at relativistic speeds has less inertia in the transverse direction than in the longitudinal one. A corollary is that the three-acceleration need not be parallel to the three-force.

#### Example 4.5.1: Circular motion

For a particle in uniform circular motion,  $\gamma$  is constant, and we have

$$F_o = \frac{d}{dt}(m\gamma v) = m\gamma \frac{dv}{dt} \quad (4.5.4)$$

The particle's mass-energy is constant, so the timelike component of  $F_o$  does happen to be zero in this example. In terms of the three-vectors  $v_o$  and  $a_o$  defined in section 3.7, we have

$$F_o = m\gamma \frac{dv_o}{dt} = m\gamma a_o \quad (4.5.5)$$

which is greater than the Newtonian value by the factor  $\gamma$ . As a practical example, in a cathode ray tube (CRT) such as the tube in an old-fashioned oscilloscope or television, a beam of electrons is accelerated up to relativistic speed. To paint a picture on the screen, the beam has to be steered by transverse forces, and since the deflection angles are small, the world-line of the beam

is approximately that of uniform circular motion. The force required to deflect the beam is greater by a factor of  $\gamma$  than would have been expected according to Newton's laws.

### Example 4.5.2: Linear motion

For accelerated linear motion in the  $x$  direction, ignoring  $y$  and  $z$ , we have a velocity vector

$$v = \frac{dr}{d\tau} \quad (4.5.6)$$

whose  $x$  component is  $\gamma v$ . Then

$$\begin{aligned} F_{o,x} &= m \frac{d(\gamma v)}{dt} \\ &= m \frac{d(\gamma)}{dt} v + m \gamma \frac{dv}{dt} \\ &= m \frac{d\gamma}{dv} \frac{dv}{dt} + m \gamma a \\ &= m (v^2 \gamma^3 a + \gamma a) \\ &= m a \gamma^3 \end{aligned}$$

The particle's apparent inertia is increased by a factor of  $\gamma^3$  due to relativity.

The results of above two examples can be combined as follows:

$$F_o = m \gamma a_{o,\perp} + m \gamma^3 a_{o,\parallel} \quad (4.5.7)$$

where the subscripts  $\perp$  and  $\parallel$  refer to the parts of  $a_o$  perpendicular and parallel to  $v_o$ .

### Transformation of the force measured by an observer

Define a frame of reference  $o$  for the inertial frame of reference of an observer who does happen to be moving along with the particle at a particular instant in time. Then  $t$  is the same as  $\tau$ , and  $F_o$  the same as  $F$ . In this frame, the particle is momentarily at rest, so the work being done on it vanishes, and the timelike components of  $F_o$  and  $F$  are both zero.

Suppose we do a Lorentz transformation from  $o$  to a new frame  $o'$ , and suppose the boost is parallel to  $F_o$  and  $F$  (which are both purely spatial in frame  $o$ ). Call this direction  $x$ . Then  $dp = (dp_t, dp_x) = (0, dp_x)$  transforms to  $dp' = (-\gamma v dp_x, \gamma dp_x)$ , so that  $F_{o',x} = dp'_x / dt' = (\gamma dp_x) / (\gamma dt) = F_{o,x}$ . The two factors of  $\gamma$  cancel, and we find that  $F_{o',x} = F_{o,x}$ .

Now let's do the case where the boost is in the  $y$  direction, perpendicular to the force. The Lorentz transformation doesn't change  $dp_y$ , so

$$\begin{aligned} F_{o',y} &= \frac{dp'_y}{dt'} \\ &= \frac{dp_y}{(\gamma dt)} \\ &= \frac{F_{o,y}}{\gamma} \end{aligned}$$

The summary of our results is as follows. Let  $F_o$  be the force acting on a particle, as measured in a frame instantaneously comoving with the particle. Then in a frame of reference moving relative to this one, we have

$$F_{o',\parallel} = F_{o,\parallel} \quad (4.5.8)$$

and

$$F_{o',\perp} = \frac{F_{o,\perp}}{\gamma} \quad (4.5.9)$$

where  $\parallel$  indicates the direction parallel to the relative velocity of the two frames, and  $\perp$  a direction perpendicular to it.

## Work

Consider the one-dimensional version of the three-force,  $F = dp/dt$ . An advantage of this quantity is that it allows us to use the Newtonian form of the (one-dimensional) work-kinetic energy relation  $dE/dx = F$  without correction. Proof:

$$\frac{dE}{dx} = \frac{dE}{dp} \frac{dp}{dt} \frac{dt}{dx} = \frac{dE}{dp} \frac{F}{v} \quad (4.5.10)$$

By implicit differentiation of the definition of mass, we find that  $dE/dp = p/E$ , and this in turn equals  $v$  by the identity proved in Example 4.3.2. This leads to the claimed result, which is valid for both massless and material particles.

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