

2.15: Solid Body

The moments of inertia of a collection of point masses distributed in three-dimensional space (or of a solid three-dimensional body, which, after all, is a collection of point masses (atoms)) with respect to axes $Oxyz$ are:

$$A = \sum m(y^2 + z^2) \quad F = \sum myz$$

$$B = \sum m(z^2 + x^2) \quad G = \sum mzx$$

$$C = \sum m(x^2 + y^2) \quad H = \sum mxy$$

Suppose that A, B, C, F, G, H , are the moments and products of inertia with respect to axes whose origin is at the centre of mass. The *parallel axes theorems* (which the reader should prove) are as follows: Let P be some point not at the centre of mass, such that the coordinates of the centre of mass with respect to axes parallel to the axes $Oxyz$ but with origin at P are $(\bar{x}, \bar{y}, \bar{z})$.

Then the moments and products of inertia with respect to the axes through P are

$$A + M(\bar{y}^2 + \bar{z}^2) \quad F + M\bar{y}\bar{z}$$

$$B + M(\bar{z}^2 + \bar{x}^2) \quad G + M\bar{z}\bar{x}$$

$$C + M(\bar{x}^2 + \bar{y}^2) \quad H + M\bar{y}\bar{x}$$

where M is the total mass.

Unless stated otherwise, in what follows we shall suppose that the moments and products of inertia under discussion are referred to a set of axes with the centre of mass as origin.

This page titled [2.15: Solid Body](#) is shared under a [CC BY-NC 4.0](#) license and was authored, remixed, and/or curated by [Jeremy Tatum](#) via [source content](#) that was edited to the style and standards of the LibreTexts platform.