

11.5ii: Heavy damping- $\gamma > 2\omega$

The motion is given by Equations 11.5.4 and 11.5.6 where, this time, k_1 and k_2 are each real and negative. For convenience, I am going to write $\lambda_1 = -k_1$ and $\lambda_2 = -k_2$. λ_1 and λ_2 both real and positive, with $\lambda_2 > \lambda_1$ given by

$$\lambda_1 = \frac{1}{2}\gamma - \sqrt{\left(\frac{1}{2}\gamma\right)^2 - \omega_0^2}, \quad \lambda_2 = \frac{1}{2}\gamma + \sqrt{\left(\frac{1}{2}\gamma\right)^2 - \omega_0^2} \quad (11.5.19)$$

The general solution for the displacement as a function of time is

$$x = Ae^{-\lambda_1 t} + Be^{-\lambda_2 t}. \quad (11.5.20)$$

The speed is given by

$$\dot{x} = -A\lambda_1 e^{-\lambda_1 t} - B\lambda_2 e^{-\lambda_2 t}. \quad (11.5.21)$$

The constants A and B depend on the initial conditions. Thus:

$$x_0 = A + B \quad (11.5.22)$$

and

$$(\dot{x})_0 = -(A\lambda_1 + B\lambda_2). \quad (11.5.23)$$

From these, we obtain

$$A = \frac{(\dot{x})_0 + \lambda_2 x_0}{\lambda_2 - \lambda_1}, \quad B = -\left[\frac{(\dot{x})_0 + \lambda_1 x_0}{\lambda_2 - \lambda_1}\right]. \quad (11.5.24)$$

✓ Example 11.5ii.1

$$x_0 \neq 0, \quad (\dot{x})_0 = 0.$$

$$x = \frac{x_0}{\lambda_2 - \lambda_1} (\lambda_2 e^{-\lambda_1 t} - \lambda_1 e^{-\lambda_2 t}). \quad (11.5.25)$$

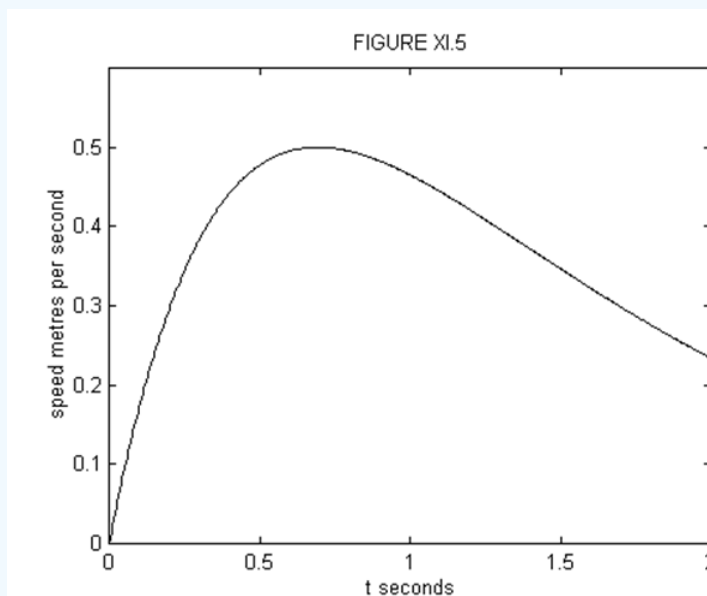
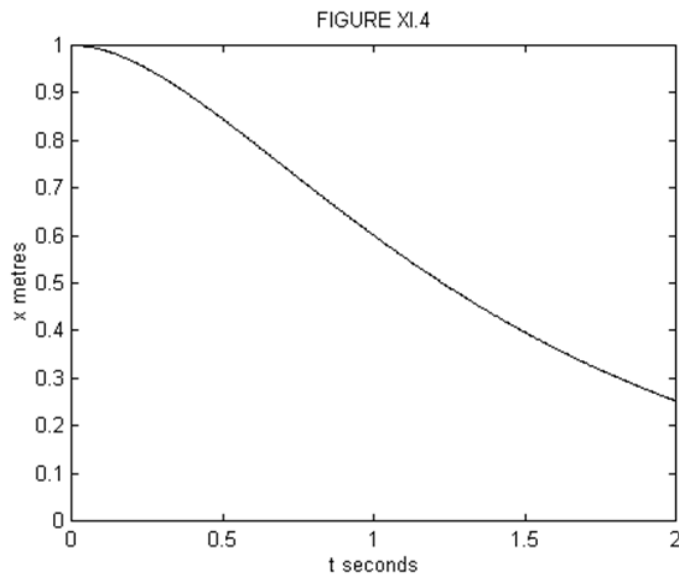
Figure XI.4 shows x vs t for $x_0 = 1$ m, $\lambda_1 = 1$ s⁻¹, $\lambda_2 = 2$ s⁻¹.

The displacement will fall to half of its initial value at a time given by putting $\frac{x}{x_0} = \frac{1}{2}$ in Equation 11.5.25. This will in general require a numerical solution. In our example, however, the equation reduces to $\frac{1}{2} = 2e^{-t} - e^{-2t}$ and if we let $u = e^{-t}$, this becomes $u^2 - 2u + \frac{1}{2} = 0$. The two solutions of this are $u = 1.707107$ or 0.292893 . The first of these gives a negative t , so we want the second solution, which corresponds to $t = 1.228$ seconds.

The velocity as a function of time is given by

$$\dot{x} = -\frac{\lambda_1 \lambda_2 x_0}{\lambda_2 - \lambda_1} (e^{-\lambda_1 t} - e^{-\lambda_2 t}). \quad (11.5.26a)$$

This is always negative. In figure XI.5, is shown the speed, which is $|\dot{x}|$ as a function of time, for our numerical example. Those who enjoy differentiating can show that the maximum speed is reached in a time $t = \ln 2$ and that the maximum speed is $\frac{\lambda_1 \lambda_2 x_0}{\lambda_2 - \lambda_1} \left[\left(\frac{\lambda_1}{\lambda_2}\right)^{\frac{\lambda_2}{\lambda_2 - \lambda_1}} - \left(\frac{\lambda_1}{\lambda_2}\right)^{\frac{\lambda_1}{\lambda_2 - \lambda_1}} \right]$. (Are these dimensionally correct?) In our example, the maximum speed, reached at $t = \ln 2 = 0.6931$ seconds, is 0.5 m s⁻¹.



✓ Example 11.5ii.2

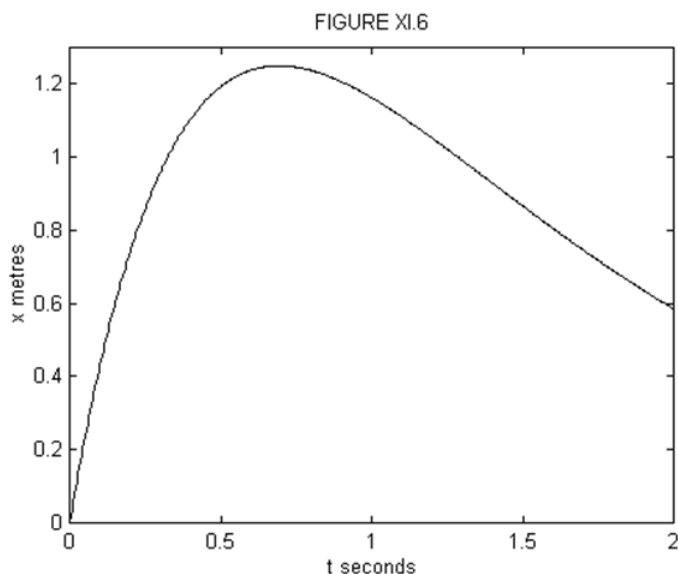
$$x_0 = 0, \quad (\dot{x})_0 = V(>0).$$

In this case it is easy to show that

$$x = \frac{V}{\lambda_2 - \lambda_1} (e^{-\lambda_1 t} - e^{-\lambda_2 t}). \quad (11.5.26b)$$

It is left as an exercise to show that x reaches a maximum value of $\frac{V}{\lambda_2} \left(\frac{\lambda_1}{\lambda_2} \right)^{\frac{\lambda_1}{\lambda_2 - \lambda_1}}$ when $t = \frac{\ln(\frac{\lambda_2}{\lambda_1})}{\lambda_2 - \lambda_1}$. Figure XI.6 illustrates Equation 11.5.26a for $\lambda_1 = 1 \text{ s}^{-1}$, $\lambda_2 = 2 \text{ s}^{-1}$, $V = 5 \text{ m s}^{-1}$. The maximum displacement of 1.25 m is reached when $t = \ln 2 = 0.6831 \text{ s}$. It is also left as an exercise to show that equation 11.5.26a can be written

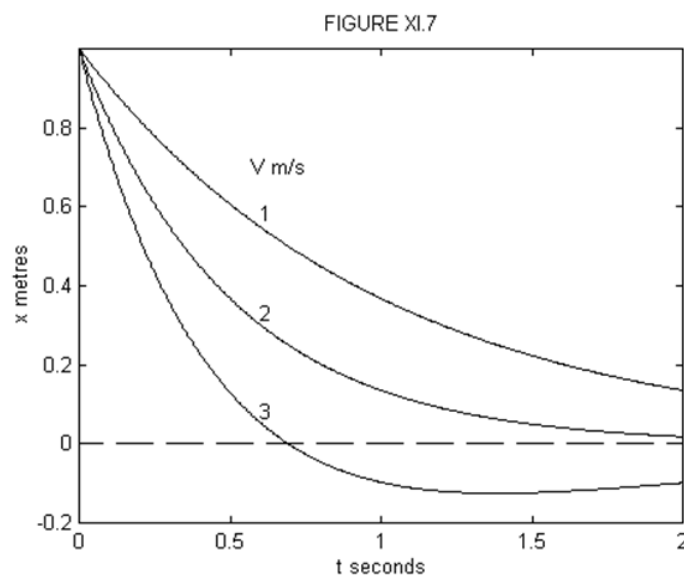
$$x = \frac{2Ve^{-\frac{1}{2}\lambda t}}{\lambda_2 - \lambda_1} \sinh\left(\frac{1}{4}\gamma^2 - \omega_0^2\right). \quad (11.5.27)$$



✓ Example 11.5ii.3

$$x_0 \neq 0, \quad (\dot{x})_0 = -V.$$

This is the really exciting example, because the suspense-filled question is whether the particle will shoot past the origin at some finite time and then fall back to the origin; or whether it will merely tamely fall down asymptotically to the origin without ever crossing it. The tension will be almost unbearable as we find out. In fact, I cannot wait; I am going to plot x versus t in figure XI.7 for $\lambda_1 = 1 \text{ s}^{-1}$, $\lambda_2 = 2 \text{ s}^{-1}$, $x_0 = 1 \text{ m}$, and three different values of V , namely 1, 2 and 3 m s^{-1} .



We see that if $V = 3 \text{ m s}^{-1}$ the particle overshoots the origin after about 0.7 seconds. If $V = 1 \text{ m s}^{-1}$, it does not look as though it will ever reach the origin. And if $V = 2 \text{ m s}^{-1}$, I'm not sure. Let's see what we can do. We can find out when it crosses the origin by putting $x = 0$ in Equation 11.5.20 where A and B are found from Equations 11.5.24 with $(\dot{x})_0 = -V$. This gives, for the time when it crosses the origin,

$$t = \frac{1}{\lambda_2 - \lambda_1} \ln\left(\frac{V - \lambda_1 x_0}{V - \lambda_2 x_0}\right). \quad (11.5.28)$$

Since $\lambda_2 > \lambda_1$, this implies that the particle will overshoot the origin if $V > \lambda_2 x_0$, and this in turn implies that, for a given V , it will overshoot only if

$$\gamma < \frac{\frac{V^2}{x_0^2} + \omega_0^2}{\frac{V}{x_0}}. \quad (11.5.29)$$

For our example, $\lambda_2 x_0 = 2 \text{ m s}^{-1}$, so that it just fails to overshoot the origin if $V = 2 \text{ m s}^{-1}$. For $V = 3 \text{ m s}^{-1}$, it crosses the origin at $t = \ln 2 = 0.6931 \text{ s}$. In order to find out how far past the origin it goes, and when, we can do this just as in

I make it that it reaches its maximum negative displacement of -0.125 m at $t = \ln 4 = 1.386 \text{ s}$.

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