

## 8.1: Introduction

As it goes about its business, a particle may experience many different sorts of forces. In Chapter 7, we looked at the effect of forces that depend only on the *speed* of the particle. In a later chapter we shall look at forces that depend only on the *position* of the particle. (Such forces will be called *conservative* forces.) In this chapter we shall look at the effect of forces that vary with *time*. Of course, it is quite possible that an unfortunate particle may be buffeted by forces that depend on its speed, on its position, and on the time - but, as far as this chapter is concerned, we shall be looking at forces that depend only on the time.

Everyone knows that Newton's second law of motion states that when a force acts on a body, the momentum of the body changes, and the rate of change of momentum is equal to the applied force. That is,  $F = \frac{dp}{dt}$ . If a force that varies with time,  $F(t)$ , acts on a body for a time  $T$ , the integral of the force over the time,  $\int_0^T F(t)dt$  is called the *impulse* of the force, and it results in a *change of momentum*  $\Delta P$  which is equal to the impulse. I shall use the symbol  $J$  to represent impulse, or the time integral of a force. Its SI units would be N s, and its dimensions  $MLT^{-1}$ , which is the same as the dimensions of momentum.

Thus, Newton's second law of motion is

$$F = \dot{p}.$$

When integrated over time, this becomes

$$J = \Delta p.$$

Likewise, in rotational motion, the *angular momentum*  $L$  of a body changes when a *torque*  $\tau$  acts on it, such that the rate of change of angular momentum is equal to the applied torque:

$$\tau = \dot{L}.$$

If the torque, which may vary with time, acts over a time  $T$ , the integral of the torque over the time,  $\int_0^T \tau dt$  is the *angular impulse*, which I shall denote by the symbol  $K$ , and it results in a change of the angular momentum:

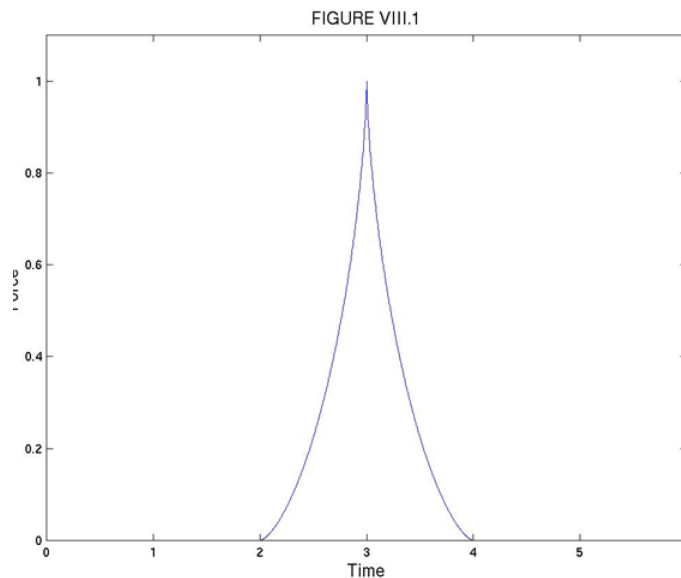
$$K = \Delta L.$$

The SI units of angular impulse are N m s, and the dimensions are  $ML^2T^{-1}$ , which are the same as those of angular momentum.

For example, suppose that a golf ball is struck by a force varies with time as

$$F = \hat{F} \left[ 1 - \left( \frac{|t - t_0|}{\tau} \right)^{\frac{2}{3}} \right]^{\frac{3}{2}}$$

This may look like a highly-contrived and unlikely function, but in Figure VIII.1 I have drawn it for  $\hat{F} = 1$ ,  $t_0 = 3$ ,  $\tau = 1$  and you will see that it is a reasonably plausible function. The club is in contact with the ball from time  $t_0 - \tau$  to  $t_0 + \tau$ .



If the ball, of mass  $m$ , starts from rest, what will be its speed  $V$  immediately after it leaves the club? The answer is that its new momentum,  $mV$ , will equal the impulse (or the time integral) of the above force:

$$mV = \hat{F} \int_{t_0-\tau}^{t_0+\tau} \left[ 1 - \left( \frac{|t-t_0|}{\tau} \right)^{\frac{2}{3}} \right]^{\frac{3}{2}} dt.$$

This is very easy to understand; if there is any difficulty it might be in the mechanics of working out this integral. It is good integration practice, but, if you can't do it after a reasonable effort, and you want a hint, ask me ([jtatum@uvic.ca](mailto:jtatum@uvic.ca)) and I'll see what I can do. You should get

$$mV = \frac{3\pi}{16} \hat{F} \tau = 0.589 \hat{F} \tau$$

#### ✓ Example 8.1.1

Here is a very similar example, except that the integration is rather easier. A ball of mass 500 g, initially at rest, is struck with a force that varies with time as

$$F = \hat{F} \left[ 1 - \left( \frac{t-t_0}{\tau} \right)^2 \right]^{\frac{1}{2}},$$

where  $\hat{F} = 4000\text{N}$ ,  $t_0 = 10\text{ ms}$ ,  $t = 3\text{ ms}$ . Draw (accurately, by computer) a graph of  $F$  versus time (it doesn't look quite like Figure VIII.1). How fast is the ball moving immediately after impact?

(I make it  $37.7\text{ m s}^{-1}$ .)

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