

## 11.2: Mass Attached to an Elastic Spring

I am thinking of a mass  $m$  resting on a smooth horizontal table, rather than hanging downwards, because I want to avoid the unimportant distraction of the gravitational force (weight) acting on the mass. The mass is attached to one end of a spring of force constant  $k$ , the other end of the spring being fixed, and the motion is restricted to one dimension.

I suppose that the force required to stretch or compress the spring through a distance  $x$  is proportional to  $x$  and to no higher powers; that is, the spring obeys *Hooke's Law*. When the spring is stretched by an amount  $x$  there is a *tension*  $kx$  in the spring; when the spring is compressed by  $x$  there is a *thrust*  $kx$  in the spring. The constant  $k$  is the *force constant* of the spring.

When the spring is stretched by an distance  $x$ , its acceleration  $\ddot{x}$  is given by

$$m\ddot{x} = -kx. \quad (11.2.1)$$

This is an Equation of the type 11.1.5, with  $\omega^2 = \frac{k}{m}$ , and the motion is therefore simple harmonic motion of period

$$P = \frac{2\pi}{\omega} = 2\pi\sqrt{\frac{m}{k}}. \quad (11.2.2)$$

At this stage you should ask yourself two things: Does this expression have dimensions T? Physically, would you expect the oscillations to be slow for a heavy mass and a weak spring? The reader might be interested to know (and this is literally true) that when I first typed Equation 11.2.2, I inadvertently typed  $\sqrt{\frac{k}{m}}$  and I immediately spotted my mistake by automatically asking myself these two questions. The reader might also like to note that you can deduce that  $P \propto \sqrt{\frac{m}{k}}$  by the method of dimensions, although you cannot deduce the proportionality constant  $2\pi$ . Try it.

*Energy Considerations.* The work required to stretch (or compress) a Hooke's law spring by  $x$  is  $\frac{1}{2}kx^2$ , and this can be described as the potential energy or the elastic energy stored in the spring. I shall not pause to derive this result here. It is probably already known by the reader, or s/he can derive it by calculus. Failing that, just consider that, in stretching the spring, the force increases linearly from 0 to  $kx$ , so the average force used over the distance  $x$  is  $\frac{1}{2}kx$  and so the work done is  $\frac{1}{2}kx^2$ .

If we assume that, while the mass is oscillating, no mechanical energy is dissipated as heat, the total energy of the system at any time is the sum of the elastic energy  $\frac{1}{2}kx^2$  stored in the spring and the kinetic energy  $\frac{1}{2}mv^2$  of the mass. (I am assuming that the mass of the spring is negligible compared with  $m$ .)

Thus

$$E = \frac{1}{2}kx^2 + \frac{1}{2}mv^2 \quad (11.2.3)$$

and there is a continual exchange of energy between elastic and kinetic. When the spring is fully extended, the kinetic energy is zero and the total energy is equal to the elastic energy then,  $\frac{1}{2}ka^2$  when the spring is unstretched and uncompressed, the energy is entirely kinetic; the mass is then moving at its maximum speed  $a\omega$  and the total energy is equal to the kinetic energy then,  $\frac{1}{2}ma^2\omega^2$ . Any of these expressions is equal to the total energy:

$$E = \frac{1}{2}kx^2 + \frac{1}{2}mv^2 = \frac{1}{2}ka^2 = \frac{1}{2}ma^2\omega^2 \quad (11.2.4)$$

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