

## 21.6: A General Central Force

Let us suppose that we have a particle that is moving under the influence of a central force  $F(r)$ . The equations of motion are

Radial:

$$m(\ddot{r} - r\dot{\theta}^2) = F(r) \quad (21.6.2)$$

Transverse:

$$r\ddot{\theta} + 2\dot{r}\dot{\theta} = 0. \quad (21.6.3)$$

These can also be written

$$\ddot{r} - \dot{\theta}^2 = a(r) \quad (21.6.4)$$

$$r^2\dot{\theta} = h. \quad (21.6.5)$$

Here  $a$  is the radial force per unit mass (i.e. the radial acceleration) and  $h$  is the (constant) angular momentum per unit mass. [If you are unsure of why Equations 21.6.3 and 21.6.5 are the same, differentiate equation 21.6.5 with respect to time.]

These are two simultaneous equations in  $r, \theta, t$ . In principle, if we could eliminate  $t$  between them, we would obtain a relation between  $r$  and  $\theta$ , which would tell us the shape of the path pursued by the particle. In Chapter 9 of my Celestial Mechanics notes we do this for the gravitational case, and we find that the path is an ellipse of the form  $r = \frac{l}{1+e \cos \theta}$ . Or perhaps we could eliminate  $r$  and hence find out how the angle  $\theta$  changes with time. Or again we might be able to eliminate  $\theta$  and hence get a relation telling us how  $r$  varies with the time. Yet again we might be told the shape of the path  $r(\theta)$ , and asked to find the force law  $F(r)$ . Or again, rather than the force, we might be given the form of the potential energy  $V(r)$ , which is related to the force by  $F = -dV/dr$ . The potential  $\Phi$  is the potential energy per unit mass, and  $-d\Phi/dr$  is the radial force per unit mass - i.e. it is the radial acceleration  $a(r)$  of the orbiting particle. The angular momentum of the particle, which is constant, is  $L = mr^2\dot{\theta}$ , and the angular momentum per unit mass is  $h = r^2\dot{\theta}$ , which is twice the rate at which the radius vector sweeps out area.

We might also remember that, if we are given the potential energy  $V$  or the potential  $\Phi$  in an inertial frame, we might also want to work in a co-rotating frame, making use of the equivalent potential energy  $V' = V + \frac{L^2}{2mr^2}$  or the equivalent potential  $\Omega' = \Omega + \frac{h^2}{2r^2}$ .

One last thing to bear in mind before starting any problems of this class. It turns out that, very often, a change of variable  $u = 1/r$  turns out to be useful. Conservation of angular momentum then takes the form  $\dot{\theta}/u^2 = h$  Also

$$\dot{r} = \frac{dr}{du} \frac{du}{dt} = \frac{dr}{d\theta} \frac{d\theta}{dt} \frac{du}{d\theta} = -\frac{\dot{\theta}}{u^2} \frac{du}{d\theta} = -h \frac{du}{d\theta} \quad (21.6.6)$$

and

$$\ddot{r} = \frac{d}{dt} \left( -h \frac{du}{d\theta} \right) = -h \frac{d}{dt} \frac{du}{d\theta} = -h \frac{d\theta}{dt} \frac{d}{d\theta} \frac{du}{d\theta} = -h \cdot hu^2 \cdot \frac{d^2u}{d\theta^2} = -h^2 u^2 \frac{d^2u}{d\theta^2}. \quad (21.6.7)$$

Equations 21.5.4 and 21.6.5 now become

$$h^2 u^2 \frac{d^2u}{d\theta^2} + h^2 u^3 = -a(r). \quad (21.6.8)$$

and

$$\dot{\theta} = hu^2. \quad (21.6.9)$$

We can now easily eliminate the time which was one of our aims:

$$h^2 u^2 \frac{d^2u}{d\theta^2} + h^2 u^3 = -a(r). \quad (21.6.10)$$

[As ever, check the dimensions.] This equation, which does not contain the time, when integrated will give us the equation to the path.

With these remarks in mind, let us try a few problems. For example:

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