

35.3: Inverse

Suppose we have vectors \mathbf{A} , \mathbf{B} , and \mathbf{C} such that $\mathbf{A} \times \mathbf{B} = \mathbf{C}$. If vectors \mathbf{B} and \mathbf{C} are known, can we solve for vector \mathbf{A} ?

There is no such thing as a "cross division" operation, so we can't do anything similar to $A = C/B$. In fact, there is no unique solution for vector \mathbf{A} . There are an infinite number of vectors that can be crossed with \mathbf{B} to yield vector \mathbf{C} ; the smaller the angle between \mathbf{A} and \mathbf{B} , the larger the magnitude A must have to yield a given vector \mathbf{C} .

To solve $\mathbf{A} \times \mathbf{B} = \mathbf{C}$ for vector \mathbf{A} , we will need to know vectors \mathbf{B} and \mathbf{C} , along with one other piece of information, such as the magnitude of vector \mathbf{A} or the angle θ between \mathbf{A} and \mathbf{B} . Suppose the magnitude A of vector \mathbf{A} is known; then since $|\mathbf{A} \times \mathbf{B}| = AB \sin \theta = C$, we have

$$\sin \theta = \frac{C}{AB} \quad (35.3.1)$$

On the other hand, if θ is known, then

$$A = \frac{C}{B \sin \theta}. \quad (35.3.2)$$

In either case, we now know both the magnitude A and the angle θ . Then since $\mathbf{A} \cdot \mathbf{B} = AB \cos \theta$, we can now find the dot product $\mathbf{A} \cdot \mathbf{B}$. Now let's take

$$\mathbf{A} \times \mathbf{B} = \mathbf{C}. \quad (35.3.3)$$

Crossing both sides on the right with vector \mathbf{B} , we get

$$(\mathbf{A} \times \mathbf{B}) \times \mathbf{B} = \mathbf{C} \times \mathbf{B}. \quad (35.3.4)$$

The left-hand side is a vector triple product; applying Eq. (32.3.8), we get

$$\mathbf{B}(\mathbf{A} \cdot \mathbf{B}) - B^2 \mathbf{A} = \mathbf{C} \times \mathbf{B} \quad (35.3.5)$$

Solving for vector \mathbf{A} , we find

$$\mathbf{A} = \frac{1}{B^2} [(\mathbf{B} \times \mathbf{C}) + (\mathbf{A} \cdot \mathbf{B})\mathbf{B}] \quad (35.3.6)$$

So if either A or θ is known, then we can find $\mathbf{A} \cdot \mathbf{B} = AB \cos \theta$; knowing this and \mathbf{B} and \mathbf{C} , Eq. (32.25) lets us solve for vector \mathbf{A} (provided $\mathbf{B}, \mathbf{C} \neq \mathbf{0}$).

35.3: Inverse is shared under a [CC BY-NC-SA 4.0](https://creativecommons.org/licenses/by-nc-sa/4.0/) license and was authored, remixed, and/or curated by LibreTexts.