

14.2: Two Coupled Linear Oscillators

Consider the two-coupled linear oscillator, shown in Figure 14.2.1, which comprises two identical masses each connected to fixed locations by identical springs having a force constant κ . A spring with force constant κ' couples the two oscillators. The equilibrium lengths of the outer two springs are l while that of the coupling spring is l' . The problem is simplified by restricting the motion to be along the line connecting the masses and assuming fixed endpoints. The small displacements of m_1 and m_2 are taken to be x_1 and x_2 with respect to the equilibrium positions l and $l+l'$ respectively. The restoring force on m_1 is $-\kappa x_1 - \kappa'(x_1 - x_2)$ while the restoring force on m_2 is $-\kappa x_2 - \kappa'(x_2 - x_1)$. This coupled double-oscillator system exhibits basic features of coupled linear oscillator systems.

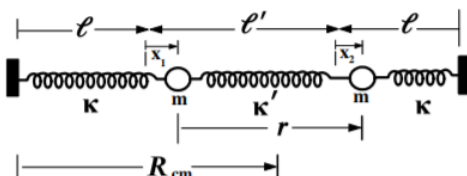


Figure 14.2.1: Two coupled linear oscillators. The equilibrium spring-lengths are l for the outer springs and l' for the coupling spring. The displacement from the stable locations are given by x_1 and x_2 . The separation between the two masses is r and the location of the center-of-mass is R_{cm} .

Assuming $m_1 = m_2 = m$, then the equations of motion are

$$\begin{aligned} m\ddot{x}_1 + (\kappa + \kappa')x_1 - \kappa'x_2 &= 0 \\ m\ddot{x}_2 + (\kappa + \kappa')x_2 - \kappa'x_1 &= 0 \end{aligned} \quad (14.2.1)$$

Assume that the motion for these coupled equations is oscillatory with a solution of the form

$$\begin{aligned} x_1 &= B_1 e^{i\omega t} \\ x_2 &= B_2 e^{i\omega t} \end{aligned} \quad (14.2.2)$$

where the constants B may be complex to take into account both the magnitude and phase. Substituting these possible solutions into the equations of motion gives

$$\begin{aligned} -m\omega^2 B_1 e^{i\omega t} + (\kappa + \kappa')B_1 e^{i\omega t} - \kappa' B_2 e^{i\omega t} &= 0 \\ -m\omega^2 B_2 e^{i\omega t} + (\kappa + \kappa')B_2 e^{i\omega t} - \kappa' B_1 e^{i\omega t} &= 0 \end{aligned} \quad (14.2.3)$$

Collecting terms, and cancelling the common exponential factor, gives

$$\begin{aligned} (\kappa + \kappa' - m\omega^2)B_1 - \kappa' B_2 &= 0 \\ (\kappa + \kappa' - m\omega^2)B_2 - \kappa' B_1 &= 0 \end{aligned} \quad (14.2.4)$$

The existence of a non-trivial solution of these two simultaneous equations requires that the determinant of the coefficients of B_1 and B_2 must vanish, that is

$$\begin{vmatrix} \kappa + \kappa' - m\omega^2 & -\kappa' \\ -\kappa' & \kappa + \kappa' - m\omega^2 \end{vmatrix} = 0 \quad (14.2.5)$$

The expansion of this secular determinant yields

$$(\kappa + \kappa' - m\omega^2)^2 - \kappa'^2 = 0 \quad (14.2.6)$$

Solving for ω gives

$$\omega = \sqrt{\frac{\kappa + \kappa' \pm \kappa'}{m}} \quad (14.2.7)$$

That is, there are two characteristic frequencies (or eigenfrequencies) for the system

$$\omega_1 = \sqrt{\frac{\kappa + 2\kappa'}{m}} \quad (14.2.8)$$

$$\omega_2 = \sqrt{\frac{\kappa}{m}} \quad (14.2.9)$$

Since superposition applies for these linear equations, then the general solution can be written as a sum of the terms that account for the two possible values of ω .

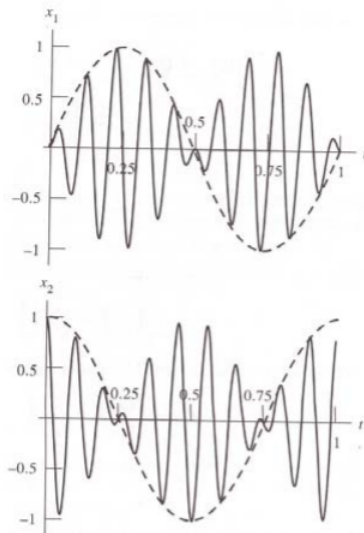


Figure 14.2.2 Displacement of each of two coupled linear harmonic oscillators with $\kappa = 4$ and $\kappa' = 1$ in relative units.

Figure 14.2.2 shows the solutions for a case where $\kappa = 4$ and $\kappa' = 1$, in arbitrary units, with the initial condition that $x_2 = D$, and $x_1 = \dot{x}_1 = \dot{x}_2 = 0$. The two characteristic frequencies are $\omega_1 = \sqrt{\frac{6}{m}}$ and $\omega_2 = \sqrt{\frac{4}{m}}$. The characteristic beats phenomenon is exhibited where the envelope over one complete cycle of the low frequency encompasses several higher frequency oscillations. That is, the solution is

$$x_2(t) = \frac{D}{4} [e^{i\omega_1 t} + e^{-i\omega_1 t} + e^{i\omega_2 t} + e^{-i\omega_2 t}] = D \cos \left[\left(\frac{\omega_1 + \omega_2}{2} \right) t \right] \cos \left[\left(\frac{\omega_1 - \omega_2}{2} \right) t \right] \quad (14.2.10)$$

while

$$x_1(t) = \frac{D}{4} [e^{i\omega_1 t} + e^{-i\omega_1 t} - e^{i\omega_2 t} - e^{-i\omega_2 t}] = D \sin \left[\left(\frac{\omega_1 + \omega_2}{2} \right) t \right] \sin \left[\left(\frac{\omega_1 - \omega_2}{2} \right) t \right] \quad (14.2.11)$$

The energy in the two-coupled oscillators flows back and forth between the coupled oscillators as illustrated in Figure 14.2.2

A better understanding of the energy flow occurring between the two coupled oscillators is given by using a (x_1, x_2) configuration-space plot, shown in Figure 14.3.1. The flow of energy occurring between the two coupled oscillators can be represented by choosing normal-mode coordinates η_1 and η_2 that are rotated by 45° with respect to the spatial coordinates (x_1, x_2) . These normal-mode coordinates (η_1, η_2) correspond to the two normal modes of the coupled double-oscillator system.

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